# University of Mumbai <br> Examination 2020 under cluster 2+5 

Curriculum Scheme: Revised 2016/2012<br>Examination: Third Year Semester V

Course Code and Course Name: MEC502 Mechanical Measurement and Control
Time: 1hour
Max. Marks: 50

College Name: A.P. Shah Institute of Technology


```
=============================================================================
```

Note to the students:- All Questions are compulsory and carry equal marks .

| Q1. | The transient response, with feedback system |
| :--- | :--- |
| Option A: | rises slowly |
| Option B: | rises quickly |
| Option C: | decays slowly |
| Option D: | decays quickly |
|  | The unit-impulse response of a system is given byc $(t)=0.5 e^{-t / 2}$. Its transfer <br> function is |
| Q2. | $\frac{1}{(s+2)}$ |
| Option A: |  |
| Option B: | $\frac{1}{(1+2 s)}$ |
| Option C: | $\frac{2}{(s+2)}$ |
| Option D: | $\frac{2}{(1+2 s)}$ |
| Q3. | If the unit-step response of a system is a unit impulse function, then the transfer <br> function of such a system will be |
| Option A: | $\frac{1}{2}$ |
| Option B: | $\frac{1}{s}$ |
| Option C: | s |
| Option D: | $\frac{1}{s^{2}}$ |
|  | Q4. |
| Option A: | Type of a system depends on the |

## University of Mumbai

Examination 2020 under cluster 2+5

| Option B: | Difference between the no. of poles and zeros |
| :---: | :---: |
| Option C: | No. of its real poles |
| Option D: | No. of poles it has at the origin |
| Q5. | A unity feedback system has open loop transfer function as $G(s)=\frac{16}{s(s+16)}$ <br> Identify the type of system |
| Option A: | Overdamped |
| Option B: | Underdamped |
| Option C: | Critically damped |
| Option D: | Undamped |
| Q6. | The settling time of a feedback system with the closed-loop transfer function $\frac{C(s)}{R(s)}=\frac{\omega^{2}}{s^{2}+2 \xi \omega s+\omega^{2}}$ |
| Option A: | $t_{s}=\frac{2}{\xi \omega}$ |
| Option B: | $t_{s}=\frac{\xi \omega}{2}$ |
| Option C: | $t_{s}=\frac{4}{\xi \omega}$ |
| Option D: | $t_{s}=4 \xi \omega$ |
| Q7. | The velocity-error constant $\mathrm{K}_{\mathrm{v}}$ of a feedback system of a closed-loop transfer function $\frac{C(s)}{R(s)}=\frac{G(s)}{1+G(s) H(s)}$ |
| Option A: | $K_{v}=\lim _{s \rightarrow 0} s G(s) H(s)$ |
| Option B: | $K_{v}=\lim _{s \rightarrow 0} s \frac{G(s)}{1+G(s) H(s)}$ |
| Option C: | $K_{v}=\lim _{s \rightarrow 0} s G(s)$ |
| Option D: | $K_{v}=\lim _{s \rightarrow 0} s[1+G(s) H(s)]$ |
| Q8. | A system has the following transfer function $G(s)=\frac{100(s+5)(s+50)}{s^{4}(s+10)\left(s^{2}+3 s+10\right)}$ <br> The type and order of the system are respectively |
| Option A: | 4 and 9 |
| Option B: | 7 and 4 |
| Option C: | 4 and 7 |
| Option D: | 9 and 4 |

## University of Mumbai

Examination 2020 under cluster 2+5

|  |  |
| :---: | :---: |
| Q9. | The step response of a system is $c(t)=1-5 e^{-t}+10 e^{-2 t}-6 e^{-3 t}$. The impulse response of the system is |
| Option A: | $5 e^{-t}-20 e^{-2 t}+18 e^{-3 t}$ |
| Option B: | $5 e^{t}-20 e^{2 t}+18 e^{-3 t}$ |
| Option C: | $5 e^{-t}+20 e^{-2 t}+18 e^{-3 t}$ |
| Option D: | $5 e^{-t}+20 e^{-2 t}-18 e^{-3 t}$ |
| Q10. | Given a unity feedback with $G(s)=\frac{K}{s(s+4)}$ <br> The value of $K$ for the damping ratio of 0.5 is |
| Option A: | 1 |
| Option B: | 9 |
| Option C: | 4 |
| Option D: | 16 |
| Q11. | In type I system, a constant output velocity at steady state will be possible, when |
| Option A: | There is no error |
| Option B: | There is a constant steady-state error |
| Option C: | There is a variable steady-state error |
| Option D: | There is a fluctuating error |
| Q12. | The impulse response of a system is $c(t)=5 e^{-10 t}$; its step response is equal to |
| Option A: | $0.5 e^{-10 t}$ |
| Option B: | $5\left(1-e^{-10 t}\right)$ |
| Option C: | $0.5\left(1-e^{-10 t}\right)$ |
| Option D: | $10\left(1-e^{-10 t}\right)$ |
| Q13. | The open loop transfer function of a system is $10 /(1+\mathrm{s})$, the steady- state error to a unit-step input will be |
| Option A: | Zero |
| Option B: | 1/11 |
| Option C: | 10 |
| Option D: | Infinity |
| Q14. | The damping ratio and natural frequency of a second-order system are 0.6 and 2 $\mathrm{rad} / \mathrm{s}$ respectively. Which of the following combinations gives the correct values of peak and settling time, respectively, for the unit-step response of the system? |
| Option A: | 3.33 s and 1.95 s |
| Option B: | 1.95 s and 1.5 s |
| Option C: | 1.95 s and 3.33 s |
| Option D: | 1.5 s and 1.95 s |
| Q15. | The steady-state error, due to a ramp input for a type-2 system, is equal to |

## University of Mumbai

Examination 2020 under cluster 2+5

| Option A: | Zero |
| :--- | :--- |
| Option B: | Infinite |
| Option C: | Non-zero number |
| Option D: | Constant |
|  |  |
| Q16. | If a second-order system has poles at $\mathbf{- 1} \pm \mathbf{j}$, then the step response of the <br> system will exhibit a peak value at |
| Option A: | 4.5 s |
| Option B: | 3.5 s |
| Option C: | 3.14 s |
| Option D: | 1 s |
|  |  |
| Q17. | Differentiation of parabolic response is a ------------- response? |
| Option A: | Parabolic |
| Option B: | Ramp |
| Option C: | Step |
| Option D: | Impulse |
|  |  |
| Q18. | The output in response to a unit step input for a particular continuous <br> control system is $\boldsymbol{c}(\boldsymbol{t})=\mathbf{1}-\boldsymbol{e}^{-2 t}$. What is the delay time Td? |
| Option A: | 0.346 |
| Option B: | 0.693 |
| Option C: | O.173 |
| Option D: | 1.386 |
|  |  |
| Q19. | Time taken by the response to reach and stay within a specified error is <br> called |
| Option A: | Raise time |
| Option B: | Peak time |
| Option C: | Delay time |
| Option D: | Settling time |
| Q22. | Consider a system with transfer function. Its damping ratio will be 0.5 when |
| Q20. | Laplace transform of unit impulse signal is: |
| Option A: | A/s |
| Option B: | A |
| Option C: | 1 |
| Option D: | $1 /$ s |
|  |  |
| Q21. | The damping ratio and peak overshoot are measures of: |
| Option A: | Relative stability |
| Option B: | Absolute stability |
| Option C: | Steady state error |
| Option D: | Speed of response |
|  |  |

## University of Mumbai

Examination 2020 under cluster 2+5

|  | the values of $k$ is: $G(s)=\frac{(s+6)}{k s^{2}+s+6}$ |
| :---: | :---: |
| Option A: | 2/6 |
| Option B: | 3 |
| Option C: | 1/6 |
| Option D: | 6 |
| Q23. | A control system, having a unit damping factor, will give |
| Option A: | A critically damped response |
| Option B: | An oscillatory response |
| Option C: | An undamped response |
| Option D: | No response |
| Q24. | A second-order system exhibits 100\% overshoot. Its damping coefficient is: |
| Option A: | Equal to 1 |
| Option B: | Equal to 0 |
| Option C: | Less than 1 |
| Option D: | Greater than 1 |
| Q25. | For a second-order system $2 \frac{d^{2} y}{d t^{2}}+4 \frac{d y}{d t}+8 y=8 x$ <br> The damping ratio is |
| Option A: | 0.1 |
| Option B: | 0.25 |
| Option C: | 0.333 |
| Option D: | 0.5 |

